

C-RED New Space New Space Applications SWIR Camera Core

Key Specifications

- 🗸 SWIR 0.9 1.7 μm
- ✓ Full Frame 600 fps
- <30 e- read noise</p>
- ✓ 640 x 512 InGaAs, 15 µm pixel pitch
- ✓ High dynamic range: 93 dB & true 16 bits
- Designed for space optical payloads
- Board level for easy integration

Key Applications

- FSO communications
- Space exploration
- Data exchange
- Cubesats
- Earth observations
- Environmental monitoring
- Gas detection



Introducing C-RED New Space



C-RED New Space is a SWIR camera core specifically tailored for satellite optical payloads. Based on a VGA InGaAs sensor with a resolution of 640x512 pixels and a 15 μ m pixel pitch, the camera is sensitive in the 0.9 to 1.7 μ m range with a quantum efficiency exceeding 70% from 1000 to 1650 nm.

C-RED New Space is an off-the-shelf SWIR camera module, for a successful seamless integration into any system,

specifically satellite optical payloads. The camera offers extensive customization in hardware, electronic design and firmware to ensure optimal performance and support the demanding conditions of space operations.

The camera offers a full frame acquisition speed of 600 frames per second and up to 32066 frames per second in 32x4 in windowing mode. Its high frame rate optimizes temporal resolution, making it invaluable for applications that involve rapid changes or movements.

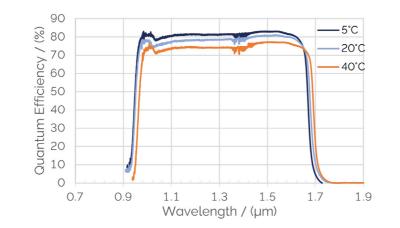


This high frame rate is combined to an extreme sensitivity and high dynamic range, without compromises. C-RED New Space offers a readout noise below 30 electrons and a 93 dB and true 16 bits high dynamic range mode: it enables imaging and sensing in ultra low light conditions and various light intensities. Additionally, the camera can operate across a large operational temperature range, making it suitable for challenging environments. Its advanced thermal design ensures low and repeatable noise, as well as maintained quantum efficiency performances.

C-RED New Space is equipped with a high-throughput CameraLink® interface, ensuring minimal latency and optimal real time capability. Other interfaces can be provided upon request. The camera is designed to be customizable both on hardware and software

aspects, and offers multiple assets for an easy integration into your system: user presets and synchronization configurations, along with onboard processing features including AGC, 2-point NUC (Non Uniformity Correction), and image flip.

Contact us to discuss your project.



Technical Specifications

Some specifications are project dependent, please contact us to discuss your specific requirements.

	C-RED New Space		
	640 x 512 pixels 0.3 Mp		
	15 µm		
Quantization		14 bit	
Readout Noise at high gain, Tint at 50 $\mu\text{s},$ 600 fps Full Frame at 5°C		<30 e-	
Flat Quantum Efficiency from 1.0 µm to 1.65 µm		>70%	
Operability due to signal response (pixels with signal ± 0.3*median at 20°C)		> 99.8 %	
Image full well capacity	low gain	1.4 Me-	
	medium gain	115 ke-	
	high gain	34 ke-	
Frame rate	full frame	600 fps	
	32 x 4 (min) pixels	32066 fps	
	320 x 256 pixels	1779 fps	
Power	Sensor: 0.5 W to 13.9 W max Stack: 6 W		

	Features
	Output
LV	Triggering
	High Dynamic Range mode
Fast conf	Configuration
De	Operating temperature
Graphical User Interface: First Lig	Software

		Frame I	rate table cro	pping mode (CameraLink®	output	
	Columns						
		32	64	128	256	512	640
	4	32066	31512	30458	28548	25367	24029
	8	28108	27348	25945	23532	19840	18397
Lines	16	22542	21631	20015	17413	13819	12526
	32	16147	15254	13736	11455	8599	7646
	64	10302	9596	8440	6801	4898	4297
	128	5975	5509	4765	3752	2632	2291
	256	3247	2975	2547	1978	1367	1184
	512	1697	1549	1319	1016	697	602

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CameraLink®

VTTL synchronization (5 V tolerant)

93 dB and true 16 bits

nfiguration switch mode (To be developed)

ependent on mechanical integration

ght Vision Software Development Kit: (C, C++, C#, Python, MatLab) / LabVIEW / µManager)



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Footnotes: Specifications are subject to change without notice



Items shipped with your camera: 1x Camera (model as ordered)

1x Power supply 1x Power supply cable

Minimum Computer Requirements:

RAM: 8 GB minimum Processor: Intel® Core™ i5 or higher Screen resolution: at least 1920 x 1080 See system requirements for more information.

Operating and Storage Conditions

Operating Temperature: Mechanical integration dependent
Camera Part Min Temperature/ °C Max Temperature/ °C
Sensor
CPU
Interface
-20
70
Backend
70
Ambient
65

 Relative Humidity: 95% (non-condensing) (Cooling off or cooling on with ambient temperature above the dew point.)

• Storage Temperature: -40°C to 60°C

Power Requirements

- 100 264 VAC 50 60 Hz
- Max. power consumption: Sensor: 0.5 W to 13.9 W max Stack: 6 W